



## Safety Concept for Cooperative HAD Vehicles

UT	Name I Narrative Definition I I of Driving I					
SAE	Name	Narrative Definition	Steering and Acceleration/	of Driving	Performance of <i>Dynamic</i>	Capability (Driving
Huma	an driver monit	ors the driving environment				
0		aspects of the <i>dynamic driving task</i> , even when enhanced	Human driver	Human driver	Human driver	n/a
1		system of either steering or acceleration/deceleration using information about the driving environment and with the expectation that the <i>human driver</i> perform all remaining		Human driver	Human driver	
2		assistance systems of both steering and acceleration/ deceleration using information about the driving environment and with the expectation that the <i>human</i> driver perform all remaining aspects of the dynamic driving	System	Human driver	Human driver	
Auto	mated driving s	ystem ("system") monitors the driving environment				
3	The second of th	the <i>driving mode</i> -specific performance by an <i>automated driving system</i> of all aspects of the dynamic driving task with the expectation that the <i>human driver</i> will respond appropriately to a <i>request to intervene</i>	System	System	Human driver	Some driving modes
4	High Automation	the <i>driving mode</i> -specific performance by an automated driving system of all aspects of the <i>dynamic driving task</i> , even if a <i>human driver</i> does not respond appropriately to a <i>request to intervene</i>	System	System	System	Some driving modes
5	Full Automation	the full-time performance by an automated driving system of all aspects of the dynamic driving task under all roadway and environmental conditions that can be managed by a human driver	System	System	System	All driving modes

Specification of Cooperative HAD Function	SAE Level	Effort	
Objectives for Cooperative HAD Function	Level 3	<ul> <li>- Highly Available Components</li> <li>- Series-grade Development Process</li> <li>- Series-grade Validation and Testing</li> </ul>	
Cooperative HAD Function under Test	Level 2	Arrangements for Safe Testing	

ARRANGEMENTS FOR SAFE	TESTING						
Safety Requirements for Cooperative HAD		Opel	Audi	BMW	Bosch	Teves	IfF
Guidelines for Test Vehicles							
Test on public roads with safety driver		<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>
Operator for supervising the sed-loop-test	e clo-	<b>√</b>	<b>√</b>	<b>√</b>	<b>✓</b>	<b>√</b>	<b>√</b>
Emergency button to interru actuator commands	ipt the	<b>✓</b>	<b>√</b>	<b>✓</b>	<b>✓</b>	<b>✓</b>	<b>√</b>
Deactivation of the driving function							
	by break pedal	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	$\checkmark$
	by activation-button	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>
	by emergency-button	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>
	by steering-wheel-torque > x Nm		<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>
	by acceleration pedal		<b>√</b>		<b>√</b>		
Activation of the driving fun	ction						
	by explicit activation through the safety driver	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>
	after system deactivation by explicit activation through the safety driver	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>
System Monitoring							
Actuator commands							
	Steering torque or similar commands	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>
	Engine torque or similar commands	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>
	Deceleration or similar commands	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>
Driver Safety							
All mounted airbags are active. Only in reasonable cases they are removed, such behind monitors.	h as		<b>√</b>	<b>√</b>			<b>~</b>
Additional parts, such as mo or buttons, are safely installe		<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>✓</b>	<b>√</b>



